LM49200 Stereo Class AB Audio Subsystem with a True Ground Headphone

Amplifier



Literature Number: SNAS459



Boomer<sup>®</sup> Audio Power Amplifier Series

# Stereo Class AB Audio Subsystem with a True Ground Headphone Amplifier

## **General Description**

The LM49200 is a fully integrated audio subsystem with a stereo power amplifier capable of delivering 500mW of continuous average power per channel into  $8\Omega$  with 1% THD+N using a 3.3V supply. The LM49200 includes a separate stereo headphone amplifier that can deliver 35mW per channel into  $32\Omega$ .

The LM49200 has three input channels. A pair of single-ended inputs and a fully differential input channel. The LM49200 features a 32-step digital volume control on the input stage and an 8-step digital volume control on the headphone output stage.

The digital volume control and output modes are programmed through a two-wire I<sup>2</sup>C compatible interface that allows flexibility in routing and mixing audio channels.

The LM49200 is designed for cellular phone, PDA, and other portable handheld applications. The high level of integration minimizes external components. The True Ground head-phone amplifier eliminates the physically large DC blocking output capacitors reducing required board space and reducing cost.

# **Key Specifications**

Supply Voltage (V <sub>DD</sub> )	$2.7 \mathrm{V} \leq \mathrm{V_{DD}} \leq 5.5 \mathrm{V}$
I <sup>2</sup> C Supply Voltage	$1.7V \le I^2 CV_{DD} \le 5.5V$
<ul> <li>Output power at V<sub>DD</sub> = 5V, 1% THD+N</li> </ul>	
$R_L = 8\Omega$ speaker	1.25W (typ)
$R_L = 32\Omega$ headphone	38mW (typ)
<ul> <li>Output power at V<sub>DD</sub> = 3.3V,</li> </ul>	

Output power at V<sub>DD</sub> = 3.3V, 1% THD+N

- $R_L = 8\Omega$  speaker
- $R_{L} = 32\Omega$  headphone 38mW (typ)
- PSRR:
  - V<sub>DD</sub> = 3.3V, 217Hz ripple, Mono In 95dB (typ)

May 21, 2009

520W (typ)

Shutdown power supply current 0.02µA (typ)

### **Features**

- Differential mono input and stereo single-ended input
- 32-step digital volume control (-80 to +18dB)
- Three independent volume channels (Left, Right, Mono)
- Separate headphone volume control
- Flexible output for speaker and headphone output
- True Ground headphone amplifier eliminates large DC blocking capacitors reducing PCB space and cost
- Receiver pass-through capability
- Soft enable function
- RF immunity topology
- "Click and Pop" suppression circuitry
- Thermal shutdown protection
- Micro-power shutdown
- I<sup>2</sup>C control interface
- Available in space-saving microSMD package

### **Applications**

Portable electronic devices

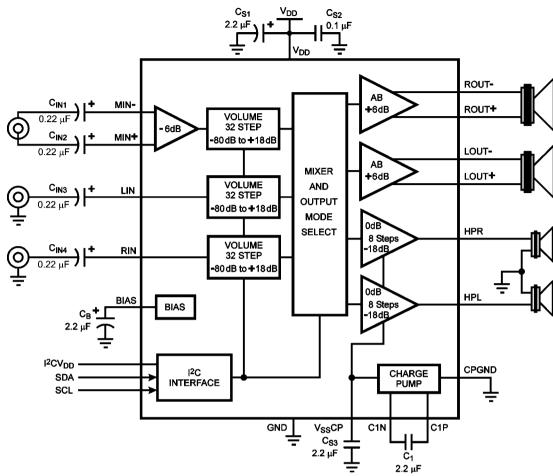
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- Mobile Phones
- PDAs

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**Typical Application** 



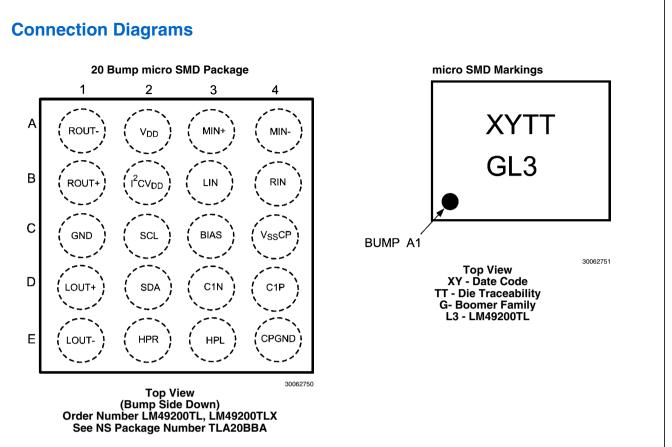
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# LM49200



## **Ordering Information**

Order Number	Package	Package DWG #	Transport Media	MSL Level	Green Status
LM49200TL	20 Bump micro SMD	TLA20BBA	250 units on tape and reel	1	RoHS and no sB/Br
LM49200TLX	20 Bump micro SMD	TLA20BBA	3000 units on tape and reel	1	RoHS and no sB/Br



# **Bump Descriptions**

Bump	Name	Pin Function	Туре
A1	ROUT-	Right Loudspeaker Negative Output	Analog Output
A2	VDD	Power Supply	Power Input
A3	MIN+	Differential Mono Positive Input	Analog Input
A4	MIN-	Differential Mono Negative Input	Analog Input
B1	ROUT+	Right Loudspeaker Positive Output	Analog Output
B2	I2CV <sub>DD</sub>	I <sup>2</sup> C power supply	Power Input
B3	LIN	Single-ended Left Input	Analog Input
B4	RIN	Single-ended Right Input	Analog Input
C1	GND	Power Ground	Ground
C2	SCL	I <sup>2</sup> C Clock	Digital Input
C3	BIAS	Half-Supply Bias point, capacitor bypassed	Analog Output
C4	VSSCP	Negative Charge Pump Power Supply	Analog Output
D1	LOUT+	Left Loudspeaker Negative Output	Analog Output
D2	SDA	I <sup>2</sup> C Data	Digital Input
D3	CIN	Negative Terminal Charge Pump Flying Capacitor	Analog Output
D4	CIP	Positive Terminal Charge Pump Flying Capacitor	Analog Output
E1	LOUT-	Left Loudspeaker Positive Output	Analog Output
E2	HPR	Right Headphone Output	Analog Output
E3	HPL	Left Headphone Output	Analog Output
E4	CPGND	Charge Pump Ground	Ground

## Absolute Maximum Ratings (Notes 1, 2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage (Note 1)	6.0V
Storage Temperature	-65°C to +150°C
Voltage at Any Input Pin	$GND - 0.3$ to $V_{DD} + 0.3V$
Power Dissipation (Note 3)	Internally Limited
ESD Rating (Note 4)	2000V
ESD Rating (Note 5)	200V
Junction Temperature (T <sub>JMAX</sub> )	150°C
Soldering Information	
Vapor Phase (60sec.)	215°C

220°C Infrared (15sec.) See AN-1112 "Micro SMD Wafer Level Chip Scale Package" Thermal Resistance θ.ιΑ

45.1°C/W

# **Operating Ratings**

**Temperature Range** 

$T_{MIN} \le T_A \le T_{MAX}$	$-40^{\circ}C \le T_A \le 85^{\circ}C$
Supply Voltage (V <sub>DD</sub> )	$2.7V \le V_{DD} \le 5.5V$
Supply Voltage (I <sup>2</sup> CV <sub>DD</sub> )	$1.7V \le I^2 CV_{DD} \le 5.5V$
	$I^2 CV_{DD} \le V_{DD}$

**Electrical Characteristics**  $V_{DD} = 3.3V$  (Notes 1, 2) The following specifications apply for  $V_{DD} = 3.3V$ ,  $T_A = 25^{\circ}$ C, all volume controls set to 0dB, unless otherwise specified.

LS = Loudspeaker, HP = Headphone.

			LM4	LM49200		
Symbol	Parameter	Conditions	Typical (Note 6)	Limits (Note 7)	Units (Limits)	
		V <sub>IN</sub> = 0, No Loads				
		EP Receiver (Output Mode Bit D4 = 1)	1.2	1.7	mA (max)	
DD	Quiescent Power Supply Current	Stereo LS only (Mode 2)	4	5.5	mA (max)	
		Stereo HP only (Mode 8)	4.5	6.4	mA (max)	
		Stereo LS + Stereo HP (Mode 10)	7.0	9.8	mA (max)	
SD	Shutdown Current		0.02	1	μA (max)	
V <sub>os</sub>	Output Offset Voltage	$V_{IN} = 0V$ , Mode 10 LS output, $R_L = 8\Omega$ BTL HP output, $R_L = 32\Omega$ SE	2.5 1.4	15 5	mV (max) mV (max)	
D	Output Downer	LS output, Mode 2, $R_L = 8\Omega$ BTL THD+N = 1%, f = 1kHz	520	450	mW (min)	
P <sub>o</sub> Output Power	HP output, Mode 8, $R_L$ = 32 $\Omega$ SE THD+N = 1%, f = 1kHz	38	35	mW (min)		
THD+N	Total Harmonic Distortion + Noise	LS output, f = 1kHz, R <sub>L</sub> = 8 $\Omega$ BTL P <sub>O</sub> = 250mW, Mode 2	0.05		%	
I HD+N	Total Harmonic Distortion + Noise	HP output, f = 1kHz, R <sub>L</sub> = $32\Omega$ SE P <sub>O</sub> = 12mW, Mode 8	0.02		%	
SNR	Signal to Naise Potio	LS output, f = 1kHz, V <sub>REF</sub> = V <sub>OUT</sub> (1%THD+N) Gain = 0dB, A-weighted LIN & RIN AC terminated	105		dB	
JNH	Signal-to-Noise Ratio	HP output, f = 1kHz, V <sub>REF</sub> = V <sub>OUT</sub> (1%THD+N) Gain = 0dB, A-weighted LIN & RIN AC terminated	101		dB	

			LM4	9200	Units (Limits)
Symbol	Symbol Parameter	Conditions	Typical (Note 6)	Limits (Note 7)	
		A-weighted, Inputs terminated to AC GND,	Output Refer	red	
		Right LS only, Mode 1	8		μV
	LS: Mode 1	8		μV	
c .	Output Noise	LS: Mode 2	11		μV
ε <sub>OUT</sub>		LS: Mode 3	14		μV
		HP: Mode 4	8		μV
		HP: Mode 8	9		μV
		HP: Mode 12	11		μV
		$V_{RIPPLE} = 200 mV_{PP}$ , $f_{RIPPLE} = 217 Hz$ , $C_B = 2$ All inputs AC terminated to GND, output ref			
PSRR Power Supply Rejection Ratio		LS: Mode 1, R <sub>L</sub> = 8Ω BTL	95		dB
	LS: Mode 2, $R_L = 8\Omega$ BTL	75		dB	
		HP: Mode 4, $R_L = 32\Omega$ SE	90		dB
		HP: Mode 8, $R_L = 32\Omega$ SE	80		dB
		f = 217Hz, V <sub>CM</sub> = 1V <sub>P-P</sub>			
CMRR	Common-Mode Rejection Ratio	LS: $R_L = 8\Omega$ BTL, Mode 1	60		dB
		HP: $R_L = 32\Omega$ SE, Mode 4	66		dB
V		LS: P <sub>O</sub> = 400mW, f = 1kHz, Mode 2	80		dB
X <sub>TALK</sub>	Crosstalk	HP: P <sub>O</sub> = 12mW, f = 1kHz, Mode 8	70		dB
7		Maximum Gain setting	12.5	10 15	kΩ (min) kΩ (max)
Z <sub>IN</sub> MIN, LIN, and RIN Input Impedance	Maximum Attenuation setting	110	90 130	k $\Omega$ (min) kΩ (max	
VOL	Digital Valume Control Dance	Maximum Gain	18		dB
VUL	Digital Volume Control Range	Maximum Attenuation	-80		dB
VOL	Volume Control Step Size Error		0.2		dB
т	Waka Lin Time from Shutdown	$C_B = 2.2 \mu F$ , HP, Normal Turn-On Mode	29		ms
Τ <sub>WU</sub>	Wake-Up Time from Shutdown	C <sub>B</sub> = 2.2µF, HP, Fast Turn-On Mode	16		ms

**Electrical Characteristics**  $V_{DD} = 5.0V$  (Notes 1, 2) The following specifications apply for  $V_{DD} = 5.0V$ ,  $T_A = 25^{\circ}C$ , all volume controls set to 0dB, unless otherwise specified.

LS = Loudspeaker, HP = Headphone.

			LM4	LM49200	
Symbol Parameter	Conditions	Typical (Note 6)	Limits (Note 7)	Units (Limits)	
		V <sub>IN</sub> = 0, No Loads			
l		EP Receiver (Output Mode Bit D4 = 1)	1.3	1.8	mA (max)
I <sub>DD</sub> Quiescent Power Supply Current	Stereo LS only (Mode 2)	4.2	5.9	mA (max)	
	Stereo HP only (Mode 8)	4.7	6.5	mA (max)	
	Stereo LS + Stereo HP (Mode 10)	7.3	10.1	mA (max)	
SD	Shutdown Current		0.02	1	μA (max)
		V <sub>IN</sub> = 0V, Mode 10			
/ <sub>os</sub>	Output Offset Voltage	LS output, $R_L = 8\Omega BTL$	2.5	15	mV (max)
		HP output, $R_L = 32\Omega$ SE	1.4	5	mV (max)

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			LM4	9200	المالية
Symbol	Parameter	Conditions	Typical (Note 6)	Limits (Note 7)	Units (Limits)
_		LS output, Mode 2, $R_L = 8\Omega$ BTL THD+N = 1%, f = 1kHz	1.25		W
Po	Output Power	HP output, Mode 8, $R_L = 32\Omega$ SE THD+N = 1%, f = 1kHz	38		mW
		LS output, f = 1kHz, R <sub>L</sub> = 8 $\Omega$ BTL P <sub>O</sub> = 400mW, Mode 2	0.05		%
THD+N	Total Harmonic Distortion + Noise	HP output, f = 1kHz, R <sub>L</sub> = $32\Omega$ SE P <sub>O</sub> = 12mW, Mode 8	0.02		%
SND	Signal to Naise Datio	LS output, f = 1kHz, $V_{REF} = V_{OUT}$ (1%THD+N) Gain = 0dB, A-weighted LIN & RIN AC terminated	109		dB
SNR Signal-to-Noise Ratio	HP output, f = 1kHz, $V_{REF} = V_{OUT}$ (1%THD+N) Gain = 0dB, A-weighted LIN & RIN AC terminated	101		dB	
		A-weighted, Inputs terminated to AC GND,	Output Refer	red	
ε <sub>OUT</sub> Output Noise	Right LS only, Mode 1	8		μV	
	LS: Mode 1	8		μV	
	LS: Mode 2	11		μV	
	LS: Mode 3	14		μV	
		HP: Mode 4	8		μV
		HP: Mode 8	9		μV
		HP: Mode 12	11		μV
		$V_{RIPPLE} = 200mV_{P-P}$ , $f_{RIPPLE} = 217Hz$ , $C_B =$ All inputs AC terminated to GND, output ref			
		LS: Mode 1, R <sub>L</sub> = 8Ω BTL	90		dB
PSRR	Power Supply Rejection Ratio	LS: Mode 2, $R_L = 8\Omega$ BTL	70		dB
		HP: Mode 4, $R_1 = 32\Omega$ SE	87		dB
		HP: Mode 8, R <sub>1</sub> = 32Ω SE	77		dB
		$f = 217Hz, V_{CM} = 1V_{P-P}$			-
CMRR	Common-Mode Rejection Ratio	LS: $R_{L} = 8\Omega$ BTL, Mode 1	60		dB
		HP: $R_L = 32\Omega$ SE, Mode 4	66		dB
		LS: $P_0 = 1W$ , f = 1kHz, Mode 2	80		dB
X <sub>TALK</sub>	Crosstalk	HP: $P_0 = 12$ mW, f = 1kHz, Mode 8	70		dB
		Maximum Gain setting	12.5		kΩ
Z <sub>IN</sub>	MIN, LIN, and RIN Input Impedance	Maximum Attenuation setting	110		kΩ
		Maximum Gain	18		dB
VOL	Digital Volume Control Range	Maximum Attenuation	-80		dB
VOL	Volume Control Step Size Error		0.2		dB
 T	Wake-Up Time from Shutdown	$C_B = 2.2\mu F$ , HP, Normal Turn-On Mode	29		ms
Τ <sub>WU</sub>	wake-op nine nom Shuldown	C <sub>B</sub> = 2.2µF, HP, Fast Turn-On Mode	16		ms

# I<sup>2</sup>C Interface (Notes 1, 2)

The following specifications apply for  $V_{DD} = 5.0V$  and 3.3V,  $2.2V \le I^2C_V_{DD} \le 5.5V$ ,  $T_A = 25^{\circ}C$ , unless otherwise specified.

		L	LM49200	
Symbol	Parameter	<b>Typical</b> (Note 4)	Limits (Notes 7, 8)	Units (Limits)
t <sub>1</sub>	I <sup>2</sup> C Clock Period		2.5	μs (min)
t <sub>2</sub>	I <sup>2</sup> C Data Setup Time		100	ns (min)
t <sub>3</sub>	I <sup>2</sup> C Data Stable Time		0	ns (min)
t <sub>4</sub>	Start Condition Time		100	ns (min)
t <sub>5</sub>	Stop Condition Time		100	ns (min)
t <sub>6</sub>	I <sup>2</sup> C Data Hold Time		100	ns (min)
V <sub>IH</sub>	I <sup>2</sup> C Input Voltage High		0.7xl <sup>2</sup> CV <sub>DD</sub>	V (min)
V <sub>IL</sub>	I <sup>2</sup> C Input Voltage Low		0.3xl <sup>2</sup> CV <sub>DD</sub>	V (max)

#### I<sup>2</sup>C Interface (Notes 1, 2)

The following specifications apply for  $V_{DD} = 5.0V$  and 3.3V,  $1.7V \le I^2C_V_{DD} \le 2.2V$ ,  $T_A = 25^{\circ}C$ , unless otherwise specified.

			L	M49200	Units
Symbol	Parameter	Conditions	Typical (Note 6)	Limits (Notes 7, 8)	(Limits)
t <sub>1</sub>	I <sup>2</sup> C Clock Period			2.5	µs (min)
t <sub>2</sub>	I <sup>2</sup> C Data Setup Time			250	ns (min)
t <sub>3</sub>	I <sup>2</sup> C Data Stable Time			0	ns (min)
t <sub>4</sub>	Start Condition Time			250	ns (min)
t <sub>5</sub>	Stop Condition Time			250	ns (min)
t <sub>6</sub>	I <sup>2</sup> C Data Hold Time			250	ns (min)
V <sub>IH</sub>	I <sup>2</sup> C Input Voltage High			0.7xl <sup>2</sup> CV <sub>DD</sub>	V (min)
V <sub>IL</sub>	I <sup>2</sup> C Input Voltage Low			0.3xl2CV <sub>DD</sub>	V (max)

**Note 1:** "Absolute Maximum Ratings" indicate limits beyond which damage to the device may occur, including inoperability and degradation of device reliability and/or performance. Functional operation of the device and/or non-degradation at the Absolute Maximum Ratings or other conditions beyond those indicated in the Recommended Operating Conditions is not implied. The Recommended Operating Conditions indicate conditions at which the device is functional and the device should not be operated beyond such conditions. All voltages are measured with respect to the ground pin, unless otherwise specified

Note 2: The *Electrical Characteristics* tables list guaranteed specifications under the listed *Recommended Operating Conditions* except as otherwise modified or specified by the *Electrical Characteristics Conditions* and/or Notes. Typical specifications are estimations only and are not guaranteed.

**Note 3:** The maximum power dissipation must be derated at elevated temperatures and is dictated by  $T_{JMAX}$ ,  $\theta_{JA}$ , and the ambient temperature,  $T_A$ . The maximum allowable power dissipation is  $P_{DMAX} = (T_{JMAX} - T_A) / \theta_{JA}$  or the number given in *Absolute Maximum Ratings*, whichever is lower.

Note 4: Human body model, applicable std. JESD22-A114C.

Note 5: Machine model, applicable std. JESD22-A115-A.

Note 6: Typical values represent most likely parametric norms at  $T_A = +25^{\circ}C$ , and at the *Recommended Operation Conditions* at the time of product characterization and are not guaranteed.

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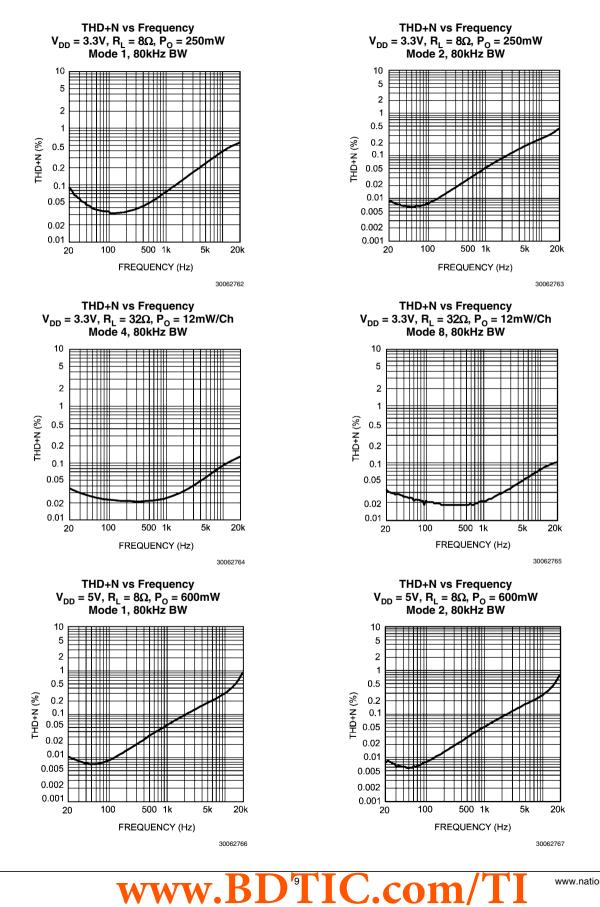
Note 7: Datasheet min/max specification limits are guaranteed by test or statistical analysis.

Note 8: Refer to the I<sup>2</sup>C timing diagram, Figure 2.

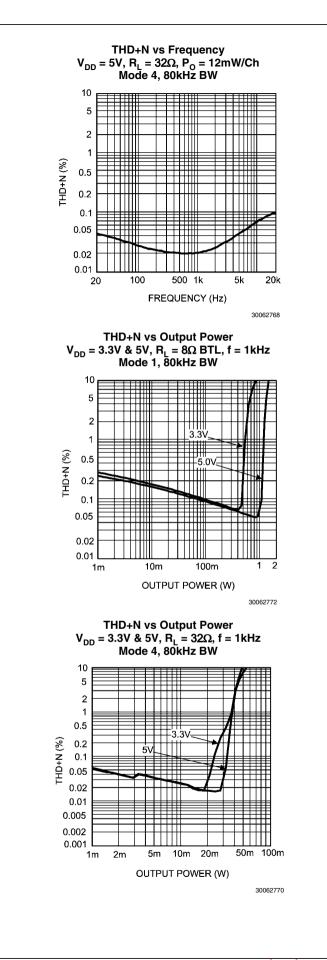
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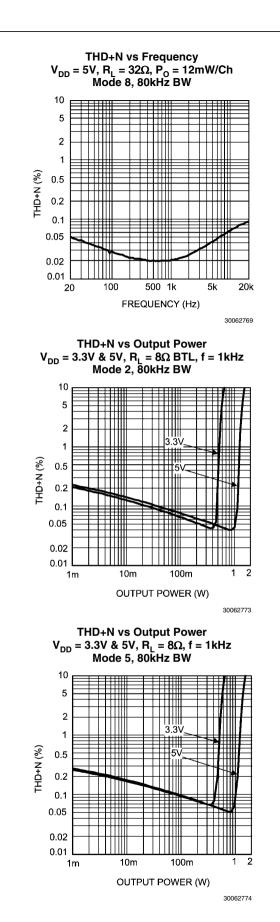
For all performance graphs, the Output Gains are set to 0dB, unless otherwise noted.

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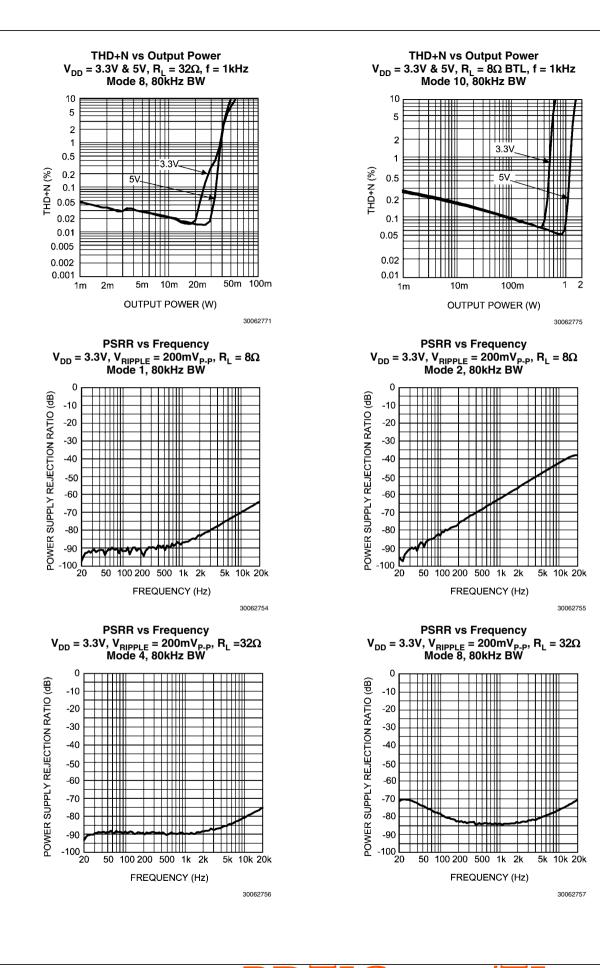


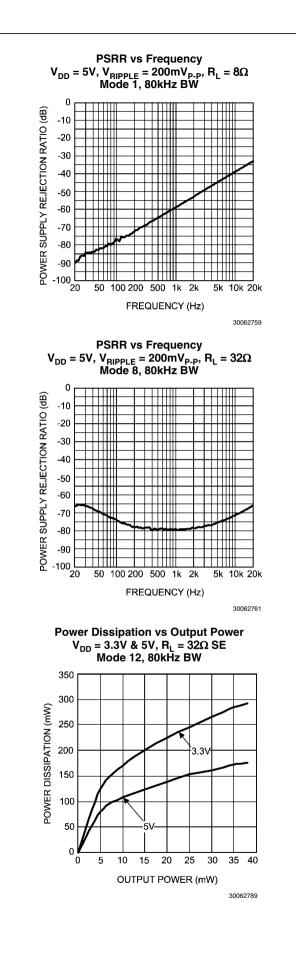
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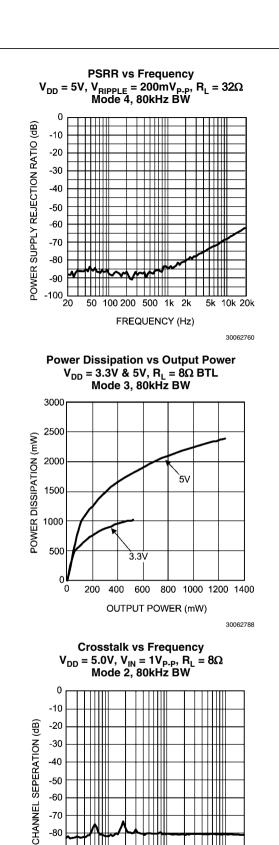




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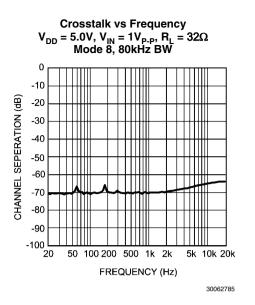
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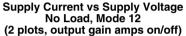
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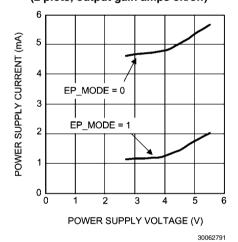
FREQUENCY (Hz)

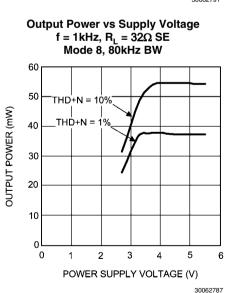
5k 10k 20k

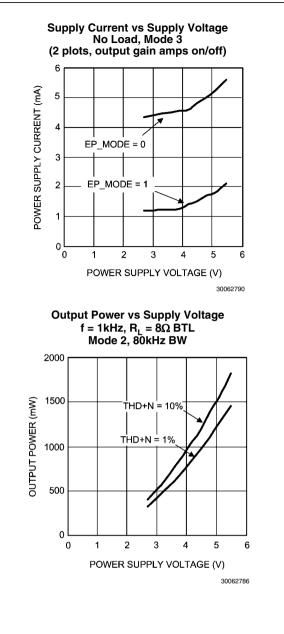
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# **Application Information**

#### I<sup>2</sup>C COMPATIBLE INTERFACE

The LM49200 is controlled through an I<sup>2</sup>C compatible serial interface that consists of a serial data line (SDA) and a serial clock (SCL). The clock line is uni-directional. The data line is bi-directional (open drain). The LM49200 and the master can communicate at clock rates up to 400kHz. Figure 2 shows the I<sup>2</sup>C interface timing diagram. Data on the SDA line must be stable during the HIGH period of SCL. The LM49200 is a transmit/receive slave-only device, reliant upon the master to generate the SCL signal. Each transmission sequence is framed by a START condition and a STOP condition (Figure 3). Each data word, device address and data, transmitted over the bus is 8 bits long and is always followed by an acknowledge pulse (Figure 4). The LM49200 device address is 11111000.

#### I<sup>2</sup>C INTERFACE POWER SUPPLY PIN (I<sup>2</sup>CV<sub>DD</sub>)

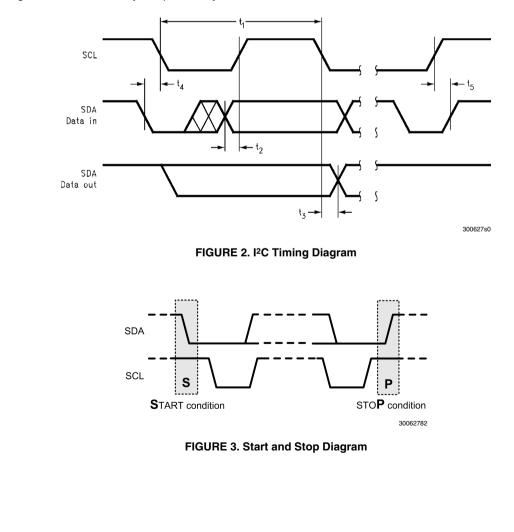
The LM49200's I<sup>2</sup>C interface is powered up through the I<sup>2</sup>CV<sub>DD</sub> pin. The LM49200's I<sup>2</sup>C interface operates at a voltage level set by the I<sup>2</sup>CV<sub>DD</sub> pin which can be set independent to that of the main power supply pin V<sub>DD</sub>. This is ideal whenever logic levels for the I<sup>2</sup>C interface are dictated by a microcontroller or microprocessor that is operating at a lower supply voltage than the main battery of a portable system

#### **I<sup>2</sup>C BUS FORMAT**

The I<sup>2</sup>C bus format is shown in Figure 4. The START signal, the transition of SDA from HIGH to LOW while SCL is HIGH, is generated, alerting all devices on the bus that a device address is being written to the bus.

The 7-bit device address is written to the bus, most significant bit (MSB) first, followed by the  $R/\overline{W}$  bit.  $R/\overline{W} = 0$  indicates the master is writing to the slave device,  $R/\overline{W} = 1$  indicates the master wants to read data from the slave device. Set  $R/\overline{W} = 0$ ; the LM49200 is a WRITE-ONLY device and will not respond to the  $R/\overline{W} = 1$ . The data is latched in on the rising edge of the clock. Each address bit must be stable while SCL is HIGH. After the last address bit is transmitted, the master device releases SDA, during which time, an acknowledge clock pulse is generated by the slave device. If the LM49200 receives the correct address, the device pulls the SDA line low, generating an acknowledge bit (ACK).

Once the master device registers the ACK bit, the 8-bit register data word is sent. Each data bit should be stable while SCL is HIGH. After the 8-bit register data word is sent, the LM49200 sends another ACK bit. Following the acknowledgement of the register data word, the master issues a STOP bit, allowing SDA to go high while SCL is high.



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R/W START MSB DEVICE ADDRESS LSB ACK MSB REGISTER DATA LSB ACK STOP SDA 30062783 FIGURE 4. Start and Stop Diagram **TABLE 1. Chip Address** Α7 A6 Α5 **A**4 A3 A2 A1 A0 Chip 0 1 1 1 1 1 0 0 Address **TABLE 2. Control Registers** Register D7 D6 D5 D4 D3 D2 D1 D0 Turn\_On Shutdown Control 0 0 0 HPR\_SD (1) 0  $I^2CV_{DD}SD^{(2)}$ Power\_On (4) Time (3) EP Mode<sup>(5)</sup> Mode Control (6) **Output Mode Control** 0 1 0 Headphone Output HP\_Gain (7) 0 0 0 0 1 Gain Control Mono Input Volume 1 0 1 Mono Vol (8) Control Left Input Volume Left\_Vol (8) 1 1 0 Control

#### Notes: All registers default to 0 on initial power-up.

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**Right Input Volume** 

Control

SCL

1. HPR\_SD: Right channel shutdown control. See Table 3.

2. I<sup>2</sup>CV<sub>DD</sub>\_SD: Control Enable Function. I<sup>2</sup>CV<sub>DD</sub> can be used to act as a hardware reset input. See Table 3.

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3. Turn\_On\_Time: Reduces the turn on time for faster activation. See Table 3.

4. Power On: Master Power on bit. See Table 3.

5. EP\_Mode: EP (Receiver) Mode control. Right loudspeaker channel can be used as earpiece path. See Table 4.

6. Mode\_Control: Sets the output mode. See Tables 4.

Right\_Vol (8)

7. HP\_Gain: Sets the headphone amplifier output gain. See Table 5

8. Mono\_Vol/Left\_Vol/Right\_Vol: Sets the input volume for Mono, Left and Right inputs. See Table 6.

#### **TABLE 3. Shutdown Control Register**

Bit	Name	Value	Description
		This bit is a mast	er shutdown control bit and sets the device to be on or off.
	Dewer On	Value	Status
0	Power_On	0	Master power off, device disable.
		1	Master power on, device enable.
		This bit sets the t	urn on time of the device.
1	Turn On Time	Value	Status
I	Turn_On_Time	0	Normal Turn-on time
		1	Fast Turn-on time
		This bit allows the	e I <sup>2</sup> C supply voltage to be used as a reset signal.
		Value	Status
2	I²CV <sub>DD</sub> _SD	0	I <sup>2</sup> CV <sub>DD</sub> acts as an active low reset input. If I <sup>2</sup> CV <sub>DD</sub> drops below 1.1V, the device resets and the I <sup>2</sup> C registers are restored to their default state.
		1	Normal Operation. I <sup>2</sup> CV <sub>DD</sub> voltage does not reset the device.
		This bit is used w	hen only one channel of the headphone amplifier is needed.
4		0	Normal headphone operation.
4	HPR_SD	1	Mono headphone output at left channel, right headphone in shutdown.

#### TABLE 4. Output Mode Control Register (see key below table)

Bits	Field	Description					
3:0	Mode_Control	These bit	nese bits determine how the input signals are mixed and routed to the outputs.				ts.
		Value	Mode	Left Loudspeaker	Right Loudspeaker	Left Headphone	Right Headphone
		0000	0	SD	SD	SD	SD
		0001	1	G <sub>M</sub> x M	G <sub>M</sub> x M	Mute	Mute
		0010	2	G <sub>L</sub> x L	G <sub>L</sub> x L	Mute	Mute
		011	3	$G_L \times L + G_M \times M$	$G_R \times R + G_M \times M$	Mute	Mute
		0100	4	SD	SD	G <sub>M</sub> x M/2	G <sub>M</sub> x M/2
		0101	5	G <sub>M</sub> x M	G <sub>M</sub> x M	G <sub>M</sub> x M/2	G <sub>M</sub> x M/2
		0110	6	G <sub>L</sub> x L	G <sub>R</sub> x R	G <sub>M</sub> x M/2	G <sub>M</sub> x M/2
		0111	7	$G_L \times L + G_M \times M$	$G_L \times L + G_M \times M$	G <sub>M</sub> x M/2	G <sub>M</sub> x M/2
		1000	8	SD	SD	G <sub>L</sub> x L	G <sub>R</sub> x R
		1001	9	G <sub>M</sub> x M	G <sub>M</sub> x M	G <sub>L</sub> x L	G <sub>R</sub> x R
		1010	10	G <sub>L</sub> x L	G <sub>R</sub> x R	G <sub>L</sub> x L	G <sub>R</sub> x R
		1011	11	$G_L \times L + G_M \times M$	$G_R \times R + G_M \times M$	G <sub>L</sub> x L	G <sub>R</sub> x R
		1100	12	SD	SD	$G_L \times L + G_M \times M/2$	G <sub>R</sub> x R + G <sub>M</sub> x M/2
		1101	13	G <sub>M</sub> x M	G <sub>M</sub> x M	$G_L \times L + G_M \times M/2$	G <sub>R</sub> x R + G <sub>M</sub> x M/2
		1110	14	G <sub>L</sub> x L	G <sub>R</sub> x R	$G_L \times L + G_M \times M/2$	G <sub>R</sub> x R + G <sub>M</sub> x M/2
		1111	15	$G_L \times L + G_M \times M$	$G_R \times R + G_M \times M$	$G_L \times L + G_M \times M/2$	G <sub>R</sub> x R + G <sub>M</sub> x M/2
4	EP Mode	This bit s	sets the loudspeaker amplifiers for earpiece mode. Status				-
		Value					
		0	Normal loudspeaker operation, control determined by bits 3:0.				
		1	Bit overrides bits 3:0. Right loudspeaker amplifier bias current reduced for low po operation. Left loudspeaker amplifier shutdown. Mono input path active and signaright loudspeaker output. Left & right input gain amplifiers shutdown for reduced p consumption.				tive and signal routed to

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M : MIN, Mono differential input

- L : LIN, Left single-ended input R : RIN, Right single-ended input

SD : Shutdown

 $G_{M}$ : Mono\_Vol setting determined by the Mono Input Volume Control register, See Table 6.

G<sub>1</sub>: Left\_Vol setting determined by the Left Input Volume Control register, See Table 6.

 $G_{R}^{L}$ : Right\_Vol setting determined by the Right Input Volume Control register, See Table 6.

#### **TABLE 5. Output Gain Control Register**

Bits	Field		Description	
2:0	HP_GAIN	These bits set the gain of the headphone output amplifiers.		
		Value	Gain (dB)	
		000	0	
		001	-1.2	
		010	-2.5	
		011	-4.0	
		100	-6.0	
		101	-8.5	
		110	-12	
		111	-18	

Bits	Fields		Description			
4:0	Mono_Vol					
	 Right_Vol	Volume Step	Value	Gain (dB)		
	Left_Vol	1	00000	-80.0		
		2	00001	-46.5		
		3	00010	-40.5		
		4	00011	-34.5		
		5	00100	-30.0		
		6	00101	-27.0		
		7	00110	-24.0		
		8	00111	-21.0		
		9	01000	-18.0		
		10	01001	-15.0		
		11	01010	-13.5		
		12	01011	-12.0		
		13	01100	-10.5		
		14	01101	-9.0		
		15	01110	-7.5		
		16	01111	-6.0		
		17	10000	-4.5		
		18	10001	-3.0		
		19	10010	-1.5		
		20	10011	0.0		
		21	10100	1.5		
		22	10101	3.0		
		23	10110	4.5		
		24	10111	6.0		
		25	11000	7.5		
		26	11001	9.0		
		27	11010	10.5		
		28	11011	12.0		
		29	11100	13.5		
		30	11101	15.0		
		31	11110	16.5		
		32	11111	18.0		

#### **TABLE 6. Input Volume Control Registers**

#### TURN\_ON\_TIME BIT

The Turn\_On\_Time bit determines the delay time from the Power\_On bit set to '1' and the internal circuits ready. For input capacitor values up to  $0.47\mu$ F the Turn\_On\_Time bit can be set to fast mode by setting the bit to a '1'. When the input capacitor values are larger than  $0.47\mu$ F then the Turn\_On\_Time bit should be set to '0' for normal turn-on time and higher delay. This allows sufficient time to charge the input capacitors to the  $\frac{1}{2}$  V<sub>DD</sub>LS bias voltage.

#### **POWER\_ON BIT**

The Power\_On bit is the master control bit to activate or deactivate the LM49200. All registers can be loaded independent of the Power\_On bit setting as long as the IC is powered correctly. Cycling the Power\_On bit does not change the values of any registers nor return all bits to the default power on value of zero. The Power\_On bit only determines whether the IC is on or off.

#### HPR\_SD BIT

The HPR\_SD bit will deactivate the right headphone output amplifier. This bit is provided to reduce power consumption when only one headphone output is needed.

#### **MODE\_CONTROL BITS**

In the LM49200 OUTPUT MODE CONTROL register (Table 4), Bit B5 (EP Bypass) controls the operation of the Earpiece Bypass path. If EP Bypass = 0, it would act under normal output mode operation set by bits B3, B2, B1, and B0. If EP Bypass = 1, it overrides the B3, B2, B1, and B0 Bits and enables the Receiver Bypass path, a class AB amplifier, to the speaker output.

Bit B4 (HPR\_SD) of the OUPUT MODE CONTROL register controls the right headphone shutdown. If HPR\_SD = 1, the right headphone output is disabled.

The LM49200 includes a comprehensive mixer multiplexer controlled through the I<sup>2</sup>C interface. The mixer/multiplexer allows any input combination to appear on any output of LM49200. Multiple input paths can be selected simultaneously. Under these conditions, the selected inputs are mixed together and output on the selected channel. Table 5 shows how the input signals are mixed together for each possible input selection.

#### **HP\_GAIN BITS**

The headphone outputs have an additional, single volume control set by the three HP\_Gain bits in the Output Gain Control register. The HP\_Gain volume setting controls the output level for both the left and the right headphone outputs.

#### LS (EP\_MODE) BIT

The LS (EP\_Mode) bit selects the amount of bias current in the loudspeaker amplifier. Setting the LS (EP\_Mode) bit to a '1' will reduce the amount of current from the  $V_{DD}$ LS supply by approximately 0.5mA. The THD performance of the loudspeaker amplifier will be reduced as a result of lower bias current. See the performance graphs in the Typical Performance Characteristics section above.

#### **VOLUME CONTROL BITS**

The LM49200 has three independent 32-step volume controls, one for each of the inputs. The five bits of the Volume Control registers sets the volume for the specified input channel.

#### SHUTDOWN FUNCTION

The LM49200 features the following shutdown controls.

Bit B4 (GAMP\_SD) of the SHUTDOWN CONTROL register controls the gain amplifiers. When GAMP\_SD = 1, it disables the gain amplifiers that are not in use. For example, in Modes 1, 4 and 5, the Mono inputs are in use, so the Left and Right input gain amplifiers are disabled, causing the  $I_{DD}$  to be minimized.

Bit B0 (PWR\_On) of the SHUTDOWN CONTROL register is the global shutdown control for the entire device. Set PWR\_On = 0 for normal operation. PWR\_On = 1 overrides any other shutdown control bit.

#### DIFFERENTIAL AMPLIFIER EXPLANATION

The LM49200 features a differential input stage, which offers improved noise rejection compared to a single-ended input amplifier. Because a differential input amplifier amplifies the difference between the two input signals, any component common to both signals is cancelled. An additional benefit of the differential input structure is the possible elimination of the DC input blocking capacitors. Since the DC component is common to both inputs, and thus cancelled by the amplifier, the LM49200 can be used without input coupling capacitors when configured with a differential input signal.

#### **BRIDGE CONFIGURATION EXPLAINED**

By driving the load differentially through the MONO outputs, an amplifier configuration commonly referred to as "bridged mode" is established. Bridged mode operation is different from the classical single-ended amplifier configuration where one side of the load is connected to ground.

A bridge amplifier design has a few distinct advantages over the single-ended configuration, as it provides differential drive to the load, thus doubling output swing for a specified supply voltage. Four times the output power is possible as compared to a single-ended amplifier under the same conditions. This increase in attainable output power assumes that the amplifier is not current limited or clipped.

A bridge configuration, such as the one used in LM49200, also creates a second advantage over single-ended amplifiers. Since the differential outputs are biased at half-supply, no net DC voltage exists across the load. This eliminates the need for an output coupling capacitor which is required in a single supply, single-ended amplifier configuration. Without an output coupling capacitor, the half-supply bias across the load would result in both increased internal IC power dissipation and also possible loudspeaker damage.

#### **POWER DISSIPATION**

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Power dissipation is a major concern when designing a successful amplifier, whether the amplifier is bridged or singleended. A direct consequence of the increased power delivered to the load by a bridge amplifier is an increase in internal power dissipation. The power dissipation of the LM49200 varies with the mode selected. The maximum power dissipation occurs in modes where all inputs and outputs are active (Modes 6, 7, 8, 9, 10, 11, 13, 14, 15). The power dissipation is dominated by the Class AB amplifier. The maximum power dissipation for a given application can be derived from the power dissipation graphs or from Equation 1.

$$P_{DMAX} = 4^{*} (V_{DD})^{2} / (2\pi^{2}R_{I})$$
(1)

It is critical that the maximum junction temperature ( $T_{JMAX}$ ) of 150°C is not exceeded.  $T_{JMAX}$  can be determined from the power derating curves by using P<sub>DMAX</sub> and the PC board foil area. By adding additional copper foil, the thermal resistance

of the application can be reduced from the free air value, resulting in higher  $P_{DMAX}$ . Additional copper foil can be added to any of the leads connected to the LM49200. It is especially effective when connected to  $V_{DD}$ , GND, and the output pins. Refer to the application information on the LM49200 reference design board for an example of good heat sinking. If  $T_{JMAX}$  still exceeds 150°C, then additional changes must be made. These changes can include reduced supply voltage, higher load impedance, or reduced ambient temperature. Internal power dissipation is a function of output power. Refer to the **Typical Performance Characteristics** curves for power dissipation information for different output powers and output loading.

#### **POWER SUPPLY BYPASSING**

As with any amplifier, proper supply bypassing is critical for low noise performance and high power supply rejection. The capacitor location on both the bypass and power supply pins should be as close to the device as possible. Typical applications employ a 5V regulator with 10µF tantalum or electrolytic capacitor and a ceramic bypass capacitor which aid in supply stability. This does not eliminate the need for bypassing the supply nodes of the LM49200. The selection of a bypass capacitor, especially  $C_{\rm B}$ , is dependent upon PSRR requirements, click and pop performance, system cost, and size constraints.

#### GROUND REFERENCED HEADPHONE AMPLIFIER

The LM49200 features a low noise inverting charge pump that generates an internal negative supply voltage. This allows the headphone outputs to be biased about GND instead of a nominal DC voltage, like traditional headphone amplifiers. Because there is no DC component, the large DC blocking capacitors (typically 220µF) are not necessary. The coupling capacitors are replaced by two small ceramic charge pump capacitors, saving board space and cost. Eliminating the output coupling capacitors also improves low frequency response. In traditional headphone amplifiers, the headphone impedance and the output capacitor from a high-pass filter that not only blocks the DC component of the output, but also attenuates low frequencies, impacting the bass response. Because the LM49200 does not require the output coupling capacitors, the low frequency response of the device is not degraded by external components. In addition to eliminating the output coupling capacitors, the ground referenced output nearly doubles the available dynamic range of the LM49200 headphone amplifiers when compared to a traditional headphone amplifier operating from the same supply voltage.

#### **INPUT CAPACITOR SELECTION**

Input capacitors may be required for some applications, or when the audio source is single-ended. Input capacitors block the DC component of the audio signal, eliminating any conflict between the DC component of the audio source and the bias voltage of the LM49200. The input capacitors create a high-pass filter with the input resistors  $R_{\rm IN}$ . The -3dB point of the high-pass filter is found using equation below.

$$f = 1 / 2\pi R_{IN}C_{IN} \quad (Hz)$$

Where the value of  $\mathrm{R}_{\mathrm{IN}}$  is given in the Electrical Characteristics Table.

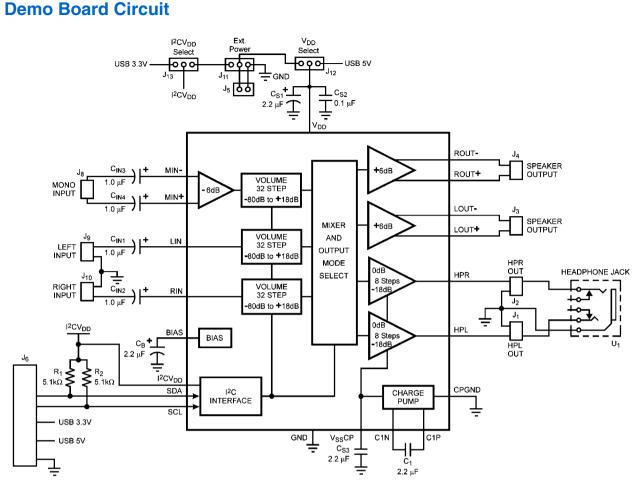
High-pass filtering the audio signal helps protect the speakers. When the LM49200 is using a single-ended source, power supply noise on the ground is seen as an input signal. Setting the high-pass filter point above the power supply noise frequencies, 217Hz in a GSM phone, for example, filters out the noise such that it is not amplified and heard on the output. Capacitors with a tolerance of 10% or better are recommended for impedance matching and improved CMRR and PSRR.

#### CHARGE PUMP FLYING CAPACITOR (C1)

The flying capacitor (C1), see Figure 1, affects the load regulation and output impedance of the charge pump. A C1 value that is too low results in a loss of current drive, leading to a loss of amplifier headroom. A higher valued C1 improves load regulation and lowers charge pump output impedance to an extent. Above  $2.2\mu$ F, the R<sub>DS(ON)</sub> of the charge pump switches and the ESR of C1 and Cs5 dominate the output impedance. A lower value capacitor can be used in systems with low maximum output power requirements.

#### CHARGE PUMP HOLD CAPACITOR (C<sub>S3</sub>)

The value and ESR of the hold capacitor (Cs5) directly affects the ripple on  $CPV_{SS}$ . Increasing the value of Cs5 reduces output ripple. Decreasing the ESR of Cs5 reduces both output ripple and charge pump output impedance. A lower value capacitor can be used in systems with low maximum output power requirements.



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LM49200

FIGURE 5. Demo Board Circuit

### **Demonstration Board**

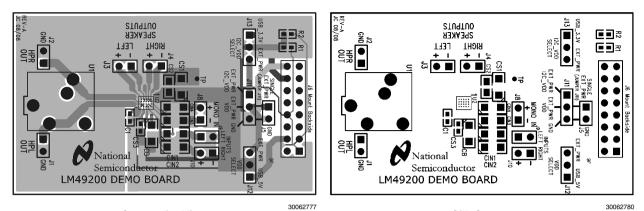
The demonstration board (see Figure 5) has connection and jumper options to be powered from the USB bus, from external power supplies or a combination of both. Additional options are to power I<sup>2</sup>CV<sub>DD</sub> and V<sub>DD</sub> from a single power supply or separate power supplies, as long as the voltage limits for each power supply are not exceeded. See the Operating Ratings for each supply's limit range. When powered from the USB bus the I<sup>2</sup>CV<sub>DD</sub> will be set to 3.3V and the V<sub>DD</sub> will be set

to 5V. Jumper headers J13 and J12 must be set accordingly. If a single power supply for I<sup>2</sup>CV<sub>DD</sub> and V<sub>DD</sub> is desired then header J5 should be used with a jumper added to header J11 to connect I2CV<sub>DD</sub> to the external supply voltage connected to J5.

Connection headers J1 and J2 are provided along with the stereo headphone jack J4 for easily connection and monitoring of the headphone outputs.

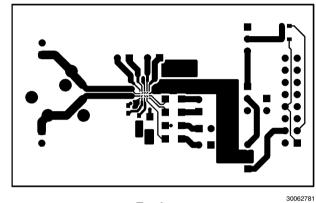


## LM49200 microSMD Demo Board Views



**Composite View** 

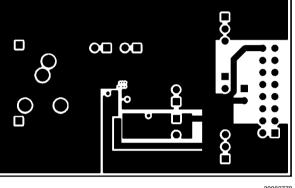




**Top Layer** 

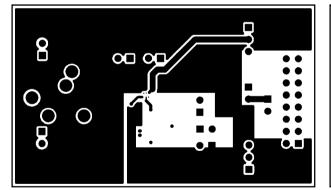
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Internal Layer 1

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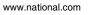


**Internal Layer 2** 

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**Bottom Layer** 

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# LM49200 Reference Demo Board Bill Of Materials

TABLE	E 7. Bill	Of Material	s
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Designator	Vlaue	Tolerance	Part Description	Comment
R <sub>1</sub> , R <sub>2</sub>	5.1kΩ	5%	1/10W, 0603 Resistors	
C <sub>IN1</sub> , C <sub>IN2</sub> C <sub>IN3</sub> , C <sub>IN4</sub>	1µF	10%	1206, X7R Ceramic Capacitor	
C <sub>S1</sub> , C <sub>B</sub>	2.2µF	10%	Size A, Tantalum Capacitor	
C <sub>S2</sub>	0.1µF	10%	0805, 16V, X7R Ceramic Capacitor	
C <sub>S3</sub> , C <sub>1</sub>	2.2µF	10%	0603, 10V, X7R Ceramic Capacitor	
U <sub>2</sub>			LM49200TL	
J <sub>1</sub> , J <sub>2</sub> , J <sub>3</sub> J <sub>4</sub> , J <sub>5</sub> , J <sub>8</sub> J <sub>9</sub> , J <sub>10</sub>			0.100" 1x2 header, vertical mount	Input, Output, V <sub>DD</sub> , GND
J <sub>11</sub> , J <sub>12</sub> , J <sub>13</sub>			0.100" 1x3 header, vertical mount	V <sub>DD</sub> Selects, V <sub>DD</sub> , I <sup>2</sup> CV <sub>DD</sub> , GND
J <sub>6</sub>			16 pin header	I <sup>2</sup> C Connector
U <sub>1</sub>			Headphone Jack	

### **PCB Layout Guidelines**

This section provides practical guidelines for mixed signal PCB layout that involves various digital/analog power and ground traces. Designers should note that these are only "rule-of-thumb" recommendations and the actual results will depend heavily on the final layout.

# General Mixed Signal Layout Recommendations

#### SINGLE-POINT POWER AND GROUND CONNECTIONS

The analog power traces should be connected to the digital traces through a single point (link). A "Pi-filter" can be helpful in minimizing high frequency noise coupling between the ana-

log and digital sections. It is further recommended to put digital and analog power traces over the corresponding digital and analog ground traces to minimize noise coupling.

#### PLACEMENT OF DIGITAL AND ANALOG COMPONENTS

All digital components and high-speed digital signals traces should be located as far away as possible from analog components and circuit traces.

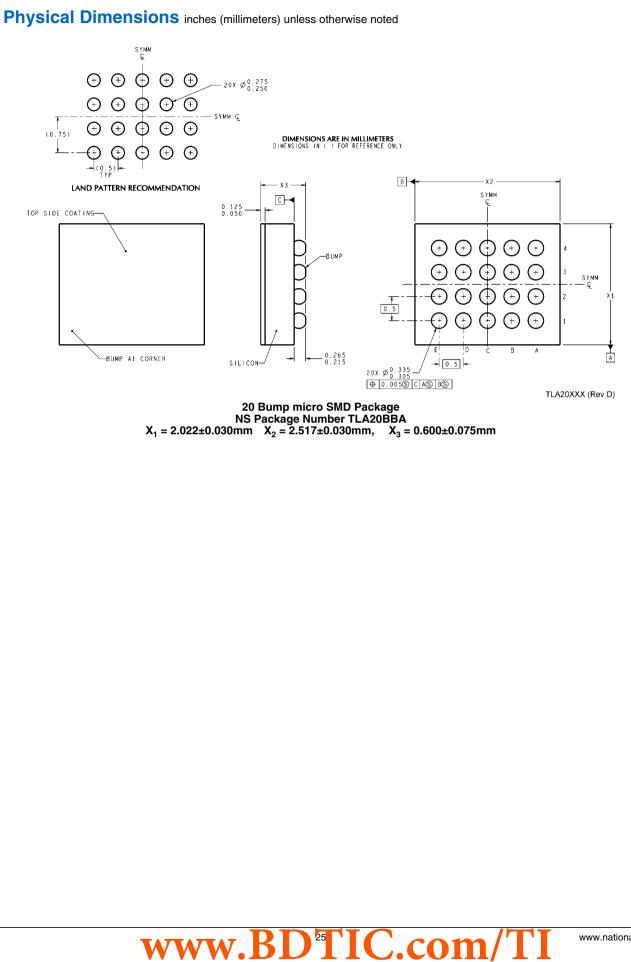
#### AVOIDING TYPICAL DESIGN AND LAYOUT PROBLEMS

Avoid ground loops or running digital and analog traces parallel to each other (side-by-side) on the same PCB layer. When traces must cross over each other do it at 90 degrees. Running digital and analog traces at 90 degrees to each other from the top to the bottom side as much as possible will minimize capacitive noise coupling and cross talk.



# **Revision History**

Rev	Date	Description
1.0	05/21/09	Initial release.



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# Notes

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LDOs	www.national.com/ldo	Quality and Reliability	www.national.com/quality
LED Lighting	www.national.com/led	Feedback/Support	www.national.com/feedback
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